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Lyapunov modes and time-correlation functions for two-dimensional systems

T. Taniguchi and G.P. Morriss

School of Physics, University of New South Wales, Sydney, New South Wales 2052, Australia

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Abstract. The relation between the Lyapunov modes (delocalized Lyapunov vectors) and the momentum autocorrelation function is discussed in two-dimensional hard-disk systems. We show numerical evidence that the smallest time-oscillating period of the Lyapunov modes is twice as long as the time-oscillating period of momentum autocorrelation function for both square and rectangular two-dimensional systems with hard-wall boundary conditions.

PACS. 05.45.Jn High-dimensional chaos – 05.45.Pq Numerical simulations of chaotic systems – 02.70.Ns Molecular dynamics and particle methods – 05.20.Jj Statistical mechanics of classical fluids

1 Introduction

The Lyapunov mode is a delocalized structure appearing in the Lyapunov vectors corresponding to the Lyapunov exponents close to zero in many-body chaotic systems. The existence of such a mode structure for Lyapunov vectors was first suggested from the stepwise structure of the Lyapunov spectra for many-hard-core-particle systems [1,2], and led to the discovery of a stationary transverse T-mode structure in the Lyapunov vectors [2–4]. Further investigations clarified the other two kinds of Lyapunov modes, the longitudinal L-mode [5] and the momentum proportional P-mode [6-8], both of which contain an explicit time-dependence. Combining these three kinds of Lyapunov modes, explained the degeneracies in the stepwise structure of Lyapunov spectra [7–9]. Moreover, the structure of these Lyapunov modes suggests that the origin of the Lyapunov modes is the dynamical conservation laws, like energy and momentum conservation, and spatial and temporal translational invariances [6–9] and Noether's theorem. The conservation laws and translational invariances dominate the global and thermodynamic behavior of many-body systems, and the behavior of Lyapunov vectors for the Lyapunov exponents close to zero should correspond to slow and collective movements. Therefore it is expected that the Lyapunov modes (which are chaotic properties) allow us to discuss the thermodynamic behavior of many-body systems dynamically. Many studies of the Lyapunov modes have used hard-core-particles in quasi-one-, two- or three-dimensional systems because of its established Lyapunov vector dynamics and clear mode structures. For example, in a Lyapunov mode for quasione-dimensional systems, the L-mode and the P-mode are coupled in the form $\delta \Gamma^{(i)} = (\delta \mathbf{x}^{(i)}, \delta \mathbf{y}^{(i)}, \delta \mathbf{p}_x^{(i)}, \delta \mathbf{p}_y^{(i)})$

where the j-th elements of $\delta \mathbf{x}^{(i)}$ and $\delta \mathbf{y}^{(i)}$ are

$$\begin{pmatrix}
\delta x_j^{(i)} \\
\delta y_j^{(i)}
\end{pmatrix} = \mathcal{A} \begin{pmatrix} p_{xj} \\
p_{yj} \end{pmatrix} \sin(\omega_i t) \cos(k_i x_j)
+ \mathcal{B} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \cos(\omega_i t) \sin(k x_j) \quad (1)$$

and $(\delta p_{xj}^{(i)}, \delta p_{yj}^{(i)}) = \mathcal{C}(\delta x_j^{(i)}, \delta y_j^{(i)})$ with constants \mathcal{A} , \mathcal{B} and \mathcal{C} . (Here, (x_j, y_j) $[(p_{xj}, p_{yj})]$ is the position (momentum) of the j-th particle with the longitudinal direction as x-axis.) Recently Lyapunov modes have been observed in soft-core particle systems [10–12]. Some analytical methods have been used to study the Lyapunov modes and the stepwise structure of Lyapunov spectra including random matrices [13], a Fokker-Planck equation [14], kinetic theory [15–17] and a periodic orbit approach [18].

One recent development in the study of Lyapunov modes is the discovery of a connection between the time dependence of the Lyapunov modes (represented by $\omega \equiv (2\pi/T_{Lya})$ for the smallest frequency of ω_i in Eq. (1)) and the momentum autocorrelation function [7,8]. The integral of the momentum autocorrelation function gives the transport coefficient (here the diffusion coefficient) through linear response theory [19]. Moreover it includes information on the collective movement of many-body systems [20–22], and is accessible experimentally using neutron and light scattering techniques [23–25]. It was shown in references [7,8] that the largest time-oscillating period T_{Lya} of time-dependent Lyapunov modes is twice as long as the time-oscillating period T_{tcf} of the momentum autocorrelation function, namely

$$T_{Lya} = 2T_{tcf}. (2)$$

This relation connects the Lyapunov mode and an experimentally accessible quantity. In reference [7,8], a theoretical argument to support this relation, and numerical evidence that this relation is independent of density, particle number, and boundary conditions in quasi-one-dimensional systems was given. The aim of this paper is to present numerical evidence that the relation (2) is satisfied not only in quasi-one-dimensional systems but also in fully two-dimensional systems.

To calculate Lyapunov exponents and Lyapunov vectors we use the Lyapunov vector dynamics for hard-disk systems [1], and the algorithm developed by Benettin et al. [26], and Shimada and Nagashima [27]. In general, the difference between two nearby phase space trajectories defines a direction in phase space. The rate of growth of this difference is controlled by the largest Lyapunov exponent, and the direction (which is time dependent) is the Lyapunov vector for that exponent. Eliminating the direction defined by the Lyapunov vector for the largest exponent, reduces the dimension of the phase space by one. In that reduced phase space we can again define a direction that corresponds to the (next) largest Lyapunov exponent and its associated Lyapunov vector. Continuing this procedure we define the same number of Lyapunov exponents and Lyapunov vectors as there are independent directions in phase space. This process is essentially the Benettin et al. scheme [26] for calculating the full spectrum of Lyapunov exponents for the system. The only additional element is the significance given to basis vectors used in the Benettin et al. scheme; here they called Lyapunov vectors and become an object of study in their own right. While the Lyapunov vectors associated with the largest exponents are strongly localized (having significant components for only a few particles) the vectors associated with the smallest positive and negative exponents have delocalized Lyapunov vectors that we refer to as Lyapunov modes.

2 A square system with 100 disks

We investigate the time-oscillating periods of the Lyapunov modes and the momentum autocorrelation function, for a system of hard-disks in a square with the hard-wall boundary conditions. Figure 1 is the Lyapunov spectrum for this system (circles). Here, we used as system parameters: N = 100, disk radius R = 1, mass M = 1, total energy E = N, and the system lengths in the x and y directions $L_x = L_y \approx 38.7$, so that the particle number density is $N(2R)^2/(L_xL_y) \approx 0.267$. The Lyapunov spectrum shows a 4-point step close to the two zero-Lyapunov exponents. We use hard-wall boundary conditions because that leads to more and clearer steps in the Lyapunov spectrum than for the equivalent system with periodic boundary conditions. In fact we do not observe stepwise structure of the Lyapunov spectrum for a 100-disk system with periodic boundary conditions. To show this, in Figure 1, we also plotted the Lyapunov spectrum for a square system with periodic boundary conditions (crosses). (Here we

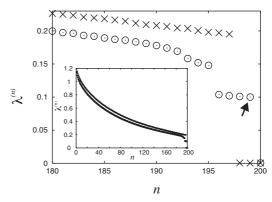


Fig. 1. The stepwise structure of Lyapunov spectrum for a square system consisting of 100 hard-disks with hard-wall boundary conditions (circles). For a comparison, the Lyapunov spectrum for a square system with periodic boundary conditions (crosses) is also shown. The Lyapunov exponent indicated by an arrow is the one in which a time-oscillation of Lyapunov mode is shown in Figure 2b. Inset: Full positive branch of Lyapunov spectra.

used the same system parameters as for hard-wall boundary conditions, except that $L_x = L_y \approx 36.7$ so the effective region available for the disks to move is the same in both cases.) The system with periodic boundary conditions is too small to observe the stepwise structure of the Lyapunov spectrum. The number of zero-Lyapunov exponents is 2 for hard-wall boundary conditions, because of energy conservation and time-translational invariance (determinisity of orbit), and is 6 for periodic boundary conditions, because of total momentum conservation, conservation of center of mass in both directions, energy conservation and time translational invariance [28]. Only half of those zero-Lyapunov exponents are presented in Figure 1.

We are interested in the time-oscillation of modes corresponding to the stepwise structure of the Lyapunov spectrum shown in Figure 1. It is known that there are two kinds of time-dependent Lyapunov modes, the L-modes and the P-modes, each with the same period [6–9]. Our concern is to determine the time-oscillating period of Lyapunov mode, so it is enough to consider one of these. We choose the L-mode and concentrate into its time-oscillating behavior only, ignoring the spatial structure [7–9]. To determine the period of the L-mode we use the same system with hard-wall boundary conditions, see Figure 1, and consider the $\delta y_j^{(2N-1)}$. This Lyapunov vector component $\delta y_j^{(2N-1)}$ corresponds to the Lyapunov exponent $\lambda^{(2N-1)}$ and is indicated by the arrow in Figure 1. To get clear time-oscillating behavior we take the average of $\delta y_i^{(2N-1)}$ for disks whose centers (x_j, y_j) are in the region $R < x_j < R + (L_x - 2R)/3$ and $R + (L_y - 2R)/3 < y_j < R + 2(L_y - 2R)/3$ (the grey region in Fig. 2a) at the time of the collisions. This region is chosen because the L-mode has a node at this end of the system, so that the longest L-mode for $\delta y_j^{(2N-1)}$ should have nodes at y=R and $L_y - 2R$ and an anti-node at $y = L_y/2$, so the Lyapunov

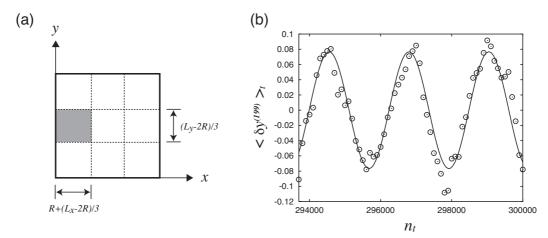


Fig. 2. (a) The spatial region of the system in which the average of the longitudinal Lyapunov mode of figure b, is taken. (b) The time-oscillation of the local spatial region for the Lyapunov vector component $\langle \delta y^{(2N-1)} \rangle_t$ for the component $dy_j^{(2N-1)}$ of the Lyapunov vector. The line is a fit of the numerical data to a sinusoidal function. The system is the same as that in Figure 1 with hard-wall boundary conditions.

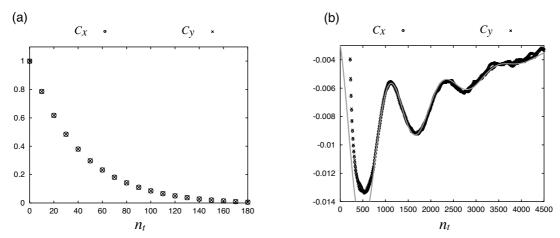
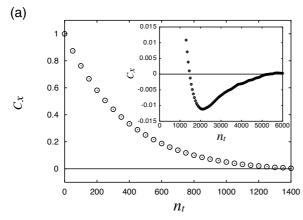


Fig. 3. The momentum autocorrelation functions as a function of the collision number n_t for a square system consisting of 100 disks. (a) The initial damping behavior of the momentum autocorrelation functions. (b) The time-oscillating region of the momentum autocorrelation functions. C_x (circles) is the autocorrelation function of the x-component and C_y (crosses) is the autocorrelation function of the y-component. These two components should be equal for a square system. The system is the same as that in Figure 2. The line in b is a fit of C_x to an exponentially damped sinusoidal function.

mode $\delta y_j^{(2N-1)}$ should have largest amplitude. Further, we take a local-time average of the spatially averaged Lyapunov vector component $\delta y_j^{(2N-1)}$ over N successive disk-disk collisions. This kind of local spatial-temporal average is required to clearly observe the time-oscillation of Lyapunov modes. A square system of N=100 particles is not large enough to observe clear mode structures in the Lyapunov vectors, as there are only about $\sqrt{N}=10$ particles in each coordinate direction. Figure 2 is a graph of the local spatial-temporal average $\langle \delta y^{(2N-1)} \rangle_t$ of $dy_j^{(2N-1)}$ as a function of the collision number n_t . In this figure we can observe the time-oscillation of the longitudinal Lyapunov mode, and the fit of the graph to a sinusoidal function $\langle \delta y^{(2N-1)} \rangle_t = \alpha \sin(2\pi n_t/T_{Lya} + \beta)$ with the fitting parameters α , β and T_{Lya} . This gives its time-oscillating period T_{Lya} as $T_{Lya} \approx 2250$. Note that T_{Lya} is in units of collision numbers n_t , and the real time interval of the

time-oscillating period of this Lyapunov mode is given by τT_{Lya} where $\tau \approx 0.0279$ is the mean free time.

Next, we consider the time-oscillating behavior of the momentum autocorrelation function. For this purpose we introduce the autocorrelation functions $C_{\eta}(t)$ of the components of momentum (where $\eta=x$ or y) and use the normalized expression $C_{\eta}(t) \equiv \tilde{C}_{\eta}(t)/\tilde{C}_{\eta}(0)$, in which $\tilde{C}_{\eta}(t)$ is defined by $\tilde{C}_{\eta}(t) \equiv \lim_{T \to +\infty} \frac{1}{NT} \sum_{j=1}^{N} \int_{0}^{T} ds \ p_{\eta j}(s+t) p_{\eta j}(s)$. Here $p_{\eta j}(s)$ is the η -component of the momentum of the j-th disk. (In numerical calculations, the time-average for the time s in the above definition of autocorrelation function is replaced by the arithmetic average of $p_{\eta j}(s+t)p_{\eta j}(s)$ after each collision.) Figure 3 shows the autocorrelation functions C_x and C_y for the x- and y-components of momenta, respectively, as functions of the collision number n_t in the same system as



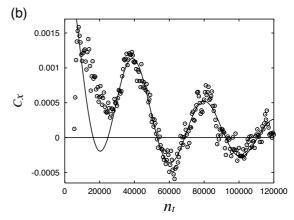


Fig. 4. The momentum autocorrelation function C_x as a function of the collision number n_t in a rectangular system consisting of 780 disks. (a) The initial damping of C_x for $0 < n_t < 1400$. Inset: The negative region of C_x for $1500 < n_t < 6000$. (b) The time-oscillating part of C_x for $10000 < n_t < 120000$. The line is a fit of C_x to an exponentially decaying sinusoidal function.

that used in Figure 2. The autocorrelation functions C_x and C_y coincide as they should for a square system. Figure 3a shows the initial damping behavior of the autocorrelation functions, and Figure 3b is the negative region in which the time-oscillating behavior of the autocorrelation functions appears. We can extract the time-oscillating period T_{tcf} by fitting this region of the autocorrelation function to the function $C_x = \alpha \exp\{-\beta n_t\} + \gamma \exp\{-\epsilon n_t\} \sin(2\pi n_t/T_{tcf} + \zeta)$ (the line in Fig. 3b) with the fitting parameters α , β , γ , ϵ , ζ and T_{tcf} . This fit gives the value of the period for the momentum autocorrelation function as $T_{tcf} \approx 1190$. Comparison of the value T_{tcf} with the longest time-oscillating period T_{Lya} for the Lyapunov modes gives further evidence to support the relation (2) in two-dimensional systems.

3 A rectangular system with 780 disks

A system of 100 particles is not sufficient to investigate the Lyapunov modes in two-dimensions as only a few steps of Lyapunov spectrum are observed, even for hard-wall boundary conditions. A larger two-dimensional system of 780 particles with hard-wall boundary conditions has already been investigated in reference [9] and the Lyapunov modes calculated. The system parameters used were: particle mass M=1, disk radius R=1/2, aspect ratio $L_y/L_x=0.867$, and particle number density $N(2R)^2/(L_xL_y)=0.8$. In this system the observed time-oscillating period for the Lyapunov mode is $T_{Lya}\tau\approx 12.80$, namely $T_{Lya}\approx 74000$ collisions numbers with the mean free time of $\tau\approx 0.000173$.

Figure 4 is the normalized autocorrelation function C_x of the x-component of the momentum as a function of the collision number n_t . Here, the system shape is rectangular and $L_x > L_y$. This means that the time-oscillating period of C_x is larger than that for C_y , and should correspond to the T_{Lya} observed in reference [9]. The autocorrelation function C_x , normalized by its initial value, shows an initial exponential damping, as shown in Figure 4a, and after that a negative region appears, as in

Figure 3 for the N=100 case. The time-oscillating behavior of C_x appears after the negative region of C_x , as shown in Figure 4b. To extract the time-oscillating period T_{tcf} for C_x we fitted this time-oscillating region of the autocorrelation function to the function $C_x = \alpha \exp\{-\beta n_t\} + \gamma \exp\{-\epsilon n_t\} \sin(2\pi n_t/T_{tcf} + \zeta)$ with the fitting parameters α , β , γ , ϵ , ζ and T_{tcf} . This fit gives us a value of $T_{tcf} \approx 40\,800$ for time-oscillating period of C_x . This result again confirms that the relation (2) is satisfied approximately for two-dimensional systems.

We emphasize that this time-oscillating behavior of the autocorrelation function C_x appears much later than its initial damping, and with a very small amplitude. (The above fit gives $\gamma \approx 0.00127$ as the amplitude of the time-oscillation of C_x shown in Figure 4b, which is much smaller than the initial value 1 for C_x .) Besides, the time-oscillation of the autocorrelation function has the time-scale much longer than its decay time. This means that very long numerical calculations are required to obtain the time-oscillating behavior of C_x in such a large system, and we calculated more than 5×10^7 collisions to get the data presented in Figures 3b and 4b. These are much longer than the simulations required to calculate Lyapunov spectra.

4 Conclusion

In conclusion, this paper gives further numerical evidence that the relation $T_{Lya} \approx 2T_{tcf}$ for the smallest time-oscillating period T_{Lya} of the Lyapunov mode and the time-oscillating period T_{tcf} of the momentum autocorrelation function is satisfied in fully two-dimensional hard-disk systems. This supports our previous results reported in references [7,8], adding numerical evidence that the relation is independent of the spatial dimension of the system.

As a remark, in this paper we used a simple fit of timeoscillation of the autocorrelation function and Lyapunov modes to functions including a sinusoidal function of time in order to extract their time-oscillating periods, as was done for the quasi-one-dimensional systems [7,8]. However, the amplitude of the time-oscillating of momentum autocorrelation function is smaller for two-dimensional systems than for quasi-one-dimensional systems. Considering the Fourier transformation of momentum autocorrelation function and Lyapunov modes may be more efficient technique to extracting the periods.

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